A Note for Cyclic 3-Dimensional Competitive Systems.

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Abstract

In this paper we consider the class C of all T-periodic competitive and dissipative 3-dimensional systems which have a cyclic in the boundary and such that the origin is a source. We use the ideas in [1] in order to give a correct proof of theorem 1.2 of [1] where we study the coexistence state for these system.

Key Words: Competitive systems, coexistence states, dissipative systems.

1 Introduction

Let C be the class of all T-periodic competitive and dissipative systems which have a cyclic in the boundary and such that the origin is a source.

In a recent paper by Tineo [1], it was proved that the property of having a coexistence state is a generic property in C with respect to a suitable topology.

Unfortunately the proof in [1] contains a mistake, but fortunately the ideas in that paper are correct and we use these in order to give a correct proof of theorem 1.2 of [1]. Our proof is based in on improvement of theorem 1.1 in that paper.

To be more precise, let us consider the system

$$x'_{i} = x_{i}F_{i}(t,x), \quad x = (x_{1}, x_{2}, x_{3}), \qquad 1 \le i \le 3,$$
(1.1)

where $F_1, F_2, F_3 : \mathbb{R} \times \mathbb{R}^3_+ \to \mathbb{R}$ are continuous functions which are Tperiodic in t and locally Lipschitz continuous in x. We shall assume that the following hypotheses hold:

- H_1) System (1.1) is competitive. That is, $F_i(t, x)$ is decreasing with respect to x_j for all $i \neq j$.
- H_2) System (1.1) is dissipative.
- H_3) $\int_0^T F_i(t,0)dt > 0$ for all *i*. This condition implies that the trivial solution is a source.

We say that (1.1) is τ -cyclic (resp. σ -cyclic) if the species x_i (resp. x_{i+1}) is carried to extinction by x_{i+1} (resp. x_i) in the subsystem obtained from (1.1) by letting $x_{i-1} = 0$, $i \in \mathbb{Z}$. (Here and henceforth we shall use the mod 3 notation).

Remark. If (H_1) holds then (H_2) is equivalent to saying the system

$$z' = zF_i(t, ze_i) \tag{1.2}$$

is dissipative for $i \leq i \leq 3$. Here and henceforth, (e_1, e_2, e_3) denotes the canonical vector basis of \mathbb{R}^3 . Thus, if (H_1) - (H_3) holds then (1.2) has a minimal positive T-periodic solution that shall denote by v_i .

In [1] is was proved that if (1.1) is τ -cyclic then,

$$I_i := \int_0^T F_{i+1}(t, v_i(t)e_i)dt \ge 0 \ge J_i := \int_0^T F_i(t, v_{i+1}(t)e_i)dt$$

Also in theorem 1.1 it was proved that if (H_1) - (H_3) hold and (1.1) is τ -cyclic, then this system has a coexistence state if $I_i > 0 \quad \forall i$. We shall complete this result as follows.

Theorem 1.1 If $J_i < 0$ $\forall i$, then (1.1) has a coexistence state.

Using this result we prove our main result.

Theorem 1.2 Let F satisfying (H_1) - (H_3) . If F is τ -cyclic then the system

$$x_i = F_i^{\epsilon}(t, x), \tag{1.3}$$

is τ -cyclic and has a coexistence state for any $\epsilon > 0$, where

$$F_i^{\epsilon}(t,x) := F_i(t,x) + \epsilon [F_i(t,x_{i+1}e_{i+1}) - F_i(t,0)] \quad \epsilon \in (0,1).$$
(1.4)

In [1], the author define,

$$F_i^{\epsilon}(t,x) := F_i(t,x) + \epsilon [F_i(t,0) - F_i(t,x_{i-1}e_{i-1})] \quad \epsilon \in (0,1).$$

but, in this case, system (1.3) is not, in general, competitive.

2 The Proofs

Proof of Theorem 1.1 Let Δ be 2-cell given by theorem 2.1 in [1] and let $\pi : \Delta \to \Delta$ the Poincare map of (1.1). We know that π is an orientation-preserving homeomorphism onto Δ . The proof of our result follows as in [1], applying the main result in [2] to π^{-1} .

Proof of Theorem 1.2 Obviously, (1.3) is competitive for all $\epsilon > 0$. On the other hand, if $z_{i+1} = 0$, we have

$$F_{i+1}^{\epsilon}(t,x) = F_{i+1}(t,x) + \epsilon [F_{i+1}(t,x_{i+2}e_{i+2}) - F_{i+1}(t,0)] \le F_{i+1}(t,x),$$

$$F_{i+2}^{\epsilon}(t,x) = F_{i+2}(t,x) + \epsilon [F_{i+2}(t,x_{i+3}e_{i+3}) - F_{i+2}(t,0)] =$$

$$= F_{i+2}(t,x) + \epsilon [F_{i+2}(t,x_{i}e_{i}) - F_{i+2}(t,0)] = F_{i+2}(t,x) \ge F_{i+2}(t,x),$$

and by proposition 4.1 of [1], (1.3) is τ -cyclic.

Note now that, the minimal positive T-periodic solution of the logistic equation $z' = zF_i^{\epsilon}(t, ze_i)$ is also v_i , since $F_i^{\epsilon}(t, ze_i) \equiv F_i(t, ze_i)$. Finally

$$\int_0^T F_i^{\epsilon}(t, v_{i+1}(t)e_{i+1})dt = (1+\epsilon)J_i - \epsilon \int_0^T F_i(t, 0)dt \le -\epsilon \int_0^T F_i(t, 0)dt < 0,$$

and the proof follows from Theorem 1.1

Remark. Let $F^{\epsilon}(t, x)$ be defined by (1.4). It is easy to show that $F^{\epsilon}(t, x) \to F(t, x)$ as $\epsilon \to 0^+$ uniformly on $\mathbb{R} \times K$ for any compact subset K of \mathbb{R} . We shall construct a family $\{F^{\epsilon}, \epsilon > 0\}$, satisfying the conclusions of Theorem 1.2, such that $F^{\epsilon}(t, x) \to F(t, x)$ as $\epsilon \to 0^+$ uniformly on $\mathbb{R} \times \mathbb{R}^3_+$. To this end let us define

$$\varphi_{i}(t,w) = \begin{cases} v_{i}(t) - \frac{1}{v_{i}(t)}[w - v_{i}(t)]^{2} & if \quad 0 \le w \le v_{i}(t) \\ \\ v_{i}(t) & if \quad w \ge v_{i}(t) \end{cases}$$

and

$$F^{\epsilon}(t,x) = F_i(t,x) + \epsilon [F_i(t,\varphi_{i+1}(t,x_{i+1})e_{i+1}) - F_i(t,0)].$$

Using the arguments in Theorem 1.2, if is easy to show that this family $\{F^{\epsilon}\}$ has the required properties.

References

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