Invariant subspaces for pairs of rotations

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A rotation in a finite-dimensional Euclidean space V is an orthogonal endomorphism $\delta \in O(V)$ whose matrix with respect to some orthonormal basis equals

$$\begin{pmatrix} R_{\alpha} & & & \\ & R_{\alpha} & & \\ & & \ddots & \\ & & & R_{\alpha} \end{pmatrix}$$

where
$$R_{\alpha} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$
 and $\alpha \in [0, \pi]$.

 $\begin{pmatrix} R_{\alpha} & & & \\ & R_{\alpha} & & \\ & & \ddots & \\ & & & R_{\alpha} \end{pmatrix}$ where $R_{\alpha} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$ and $\alpha \in [0, \pi]$.

We show that whenever (δ, ϵ) is a pair of rotations in a Euclidean space V, there exists a decomposition $V = \bigcap V$, of V into (δ, ϵ) invariant, poinwise V, there exists a decomposition $V = \bigoplus_i V_i$ of V into (δ, ϵ) -invariant, pairwise orthogonal subspaces, such that dim $V_i \leqslant 4$ for all i. This leads to a classification of all real representations of the two loop quiver given by pairs of endomorphisms of this type, up to orthogonal isomorphism.